

# Pest risk mapping based on spatial and temporal distribution of production

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# Aim

- Develop a simple methodology
  - that ranks production locations of a crop species according to the probability of pest invasion
  - based on the spatial distribution of the crop species during the past 5-10 years
- enables more efficient targeting of the plant health surveys

# Framework

- Not pest specific – crop specific!
- Based on multiyear spatial distribution of a crop species.
- Modelling is performed on a  $0.5 \times 0.5$  km grid and the results are presented as cell-specific risk indices.
- Indices do not represent actual probabilities, but they allow comparison of the relative probabilities.

# Relative probability of invasion

Assessed to each cell followingly

1. Probability of **entry**
  2. Probability of **spread**
  3. Probability of **survival**
- Probability of **invasion**

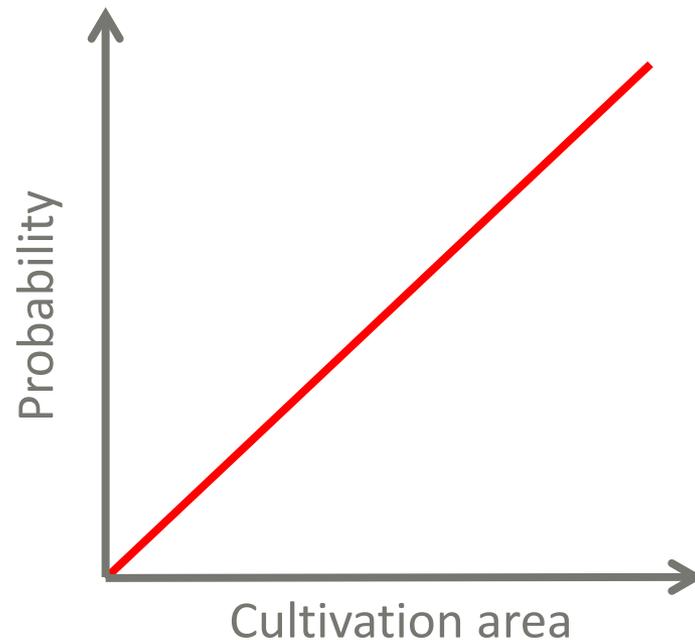
# Relative probability of invasion

Assessed to each cell followingly

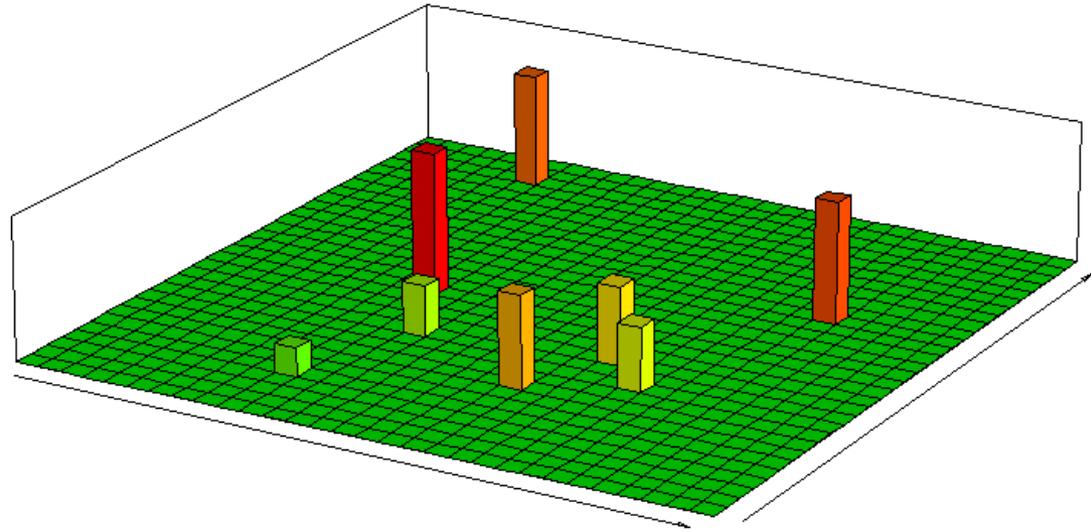
1. Probability of **entry**
  2. Probability of **spread**
  3. Probability of **survival**
- Probability of **invasion**

# 1) Relative probability of entry

to a cell is assumed to depend linearly on the cultivation area of the studied crop plant in that cell



# 1. Entry



# Relative probability of invasion

Assessed to each cell followingly

1. Probability of **entry**

2. Probability of **spread**

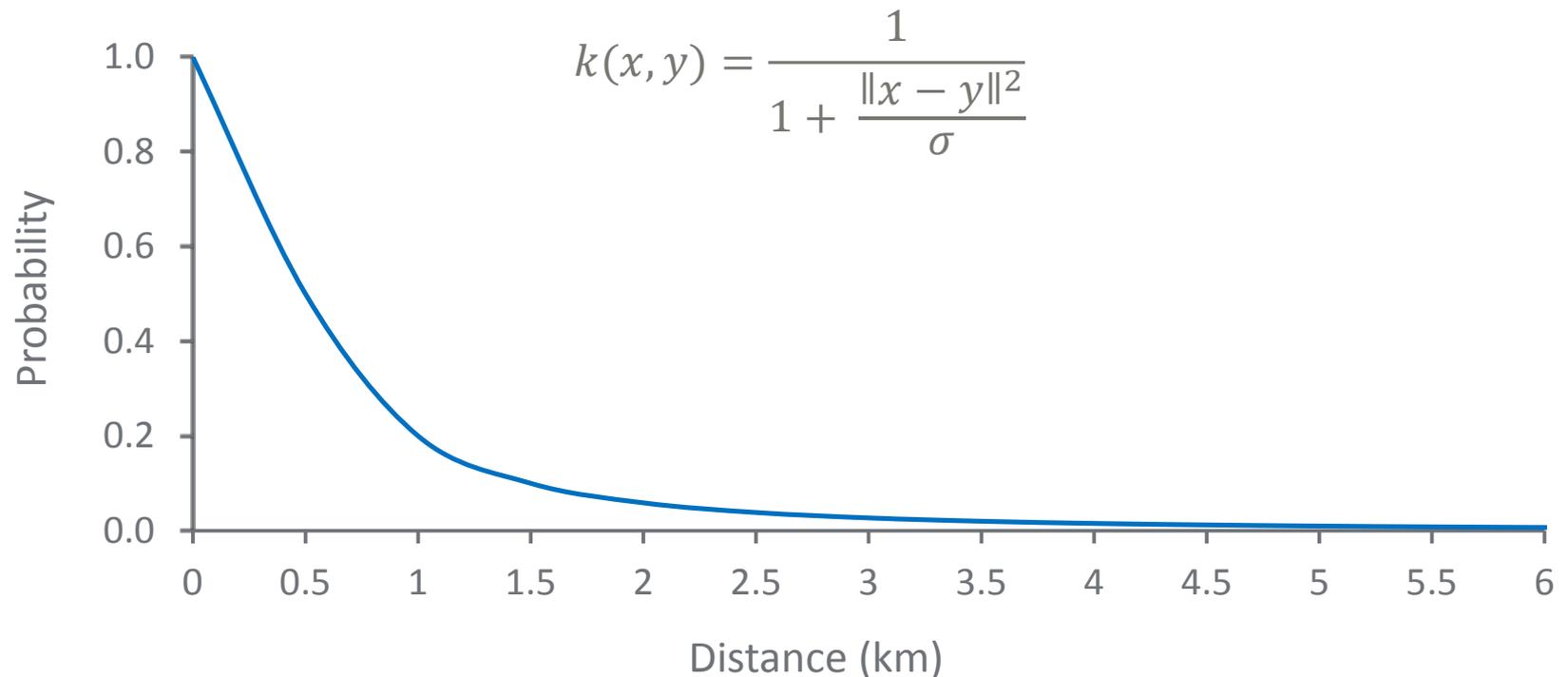
3. Probability of **survival**

→ Probability of **invasion**

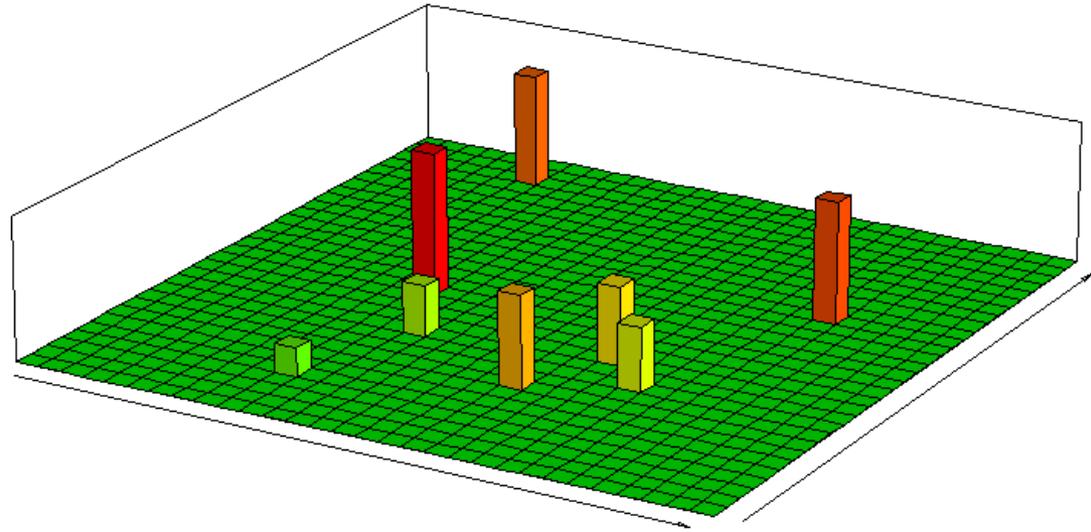
## 2) Relative probability of spread

to the surrounding cells is assumed to be distance-dependent

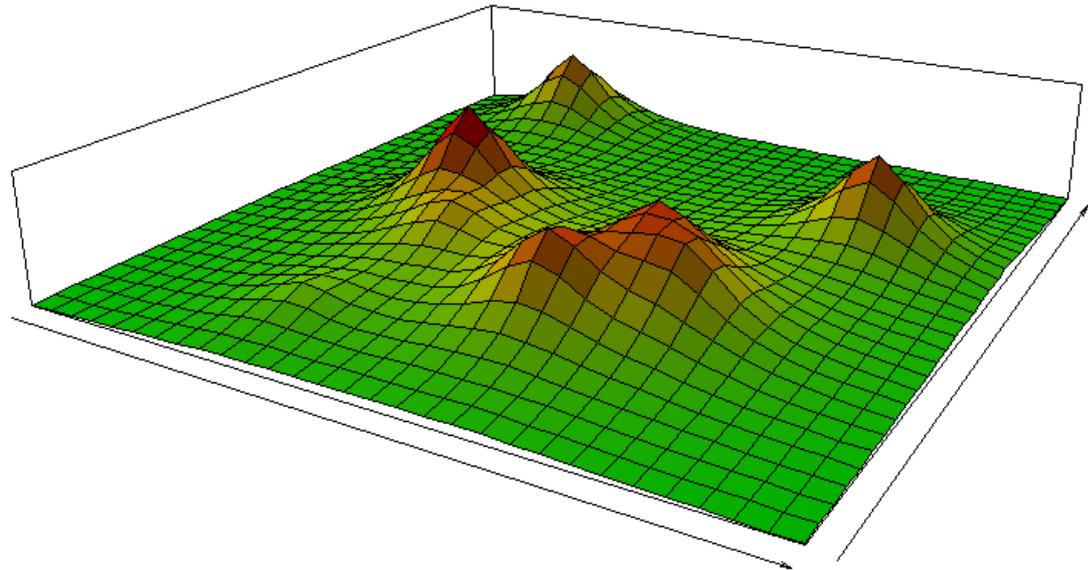
- Modeled with a Cauchy dispersal kernel



1. Entry



2. Spread



# Relative probability of invasion

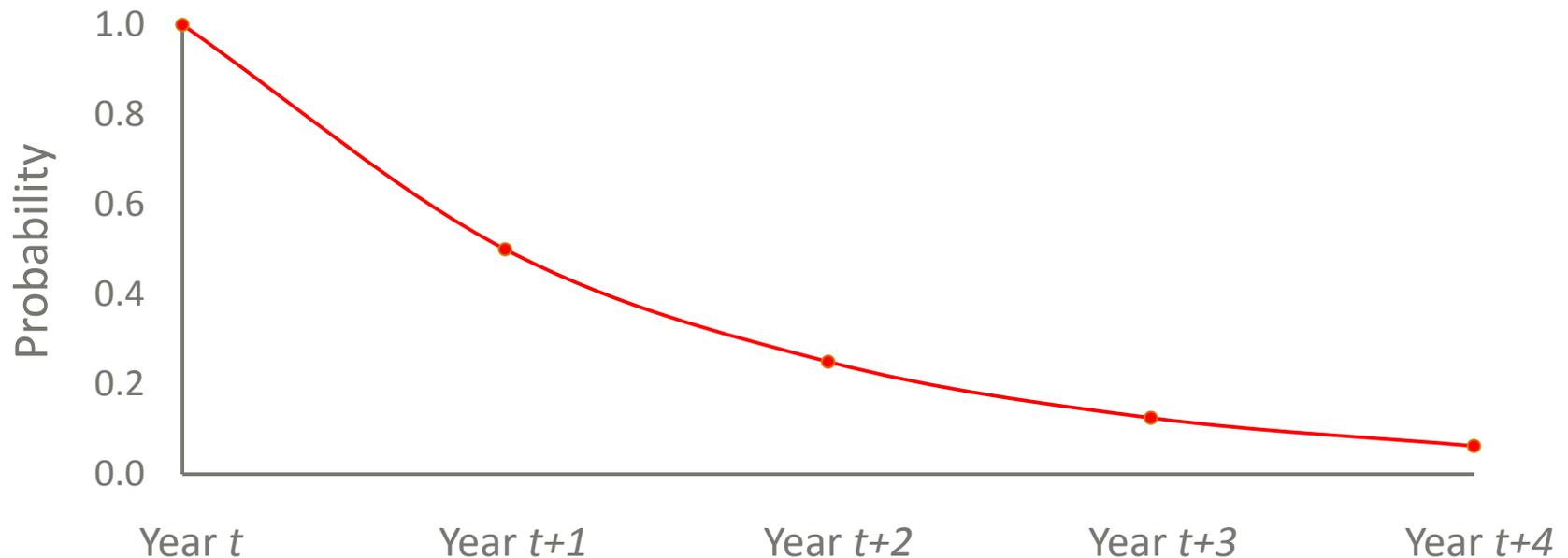
Assessed to each cell followingly

1. Probability of **entry**
  2. Probability of **spread**
  3. Probability of **survival**
- Probability of **invasion**

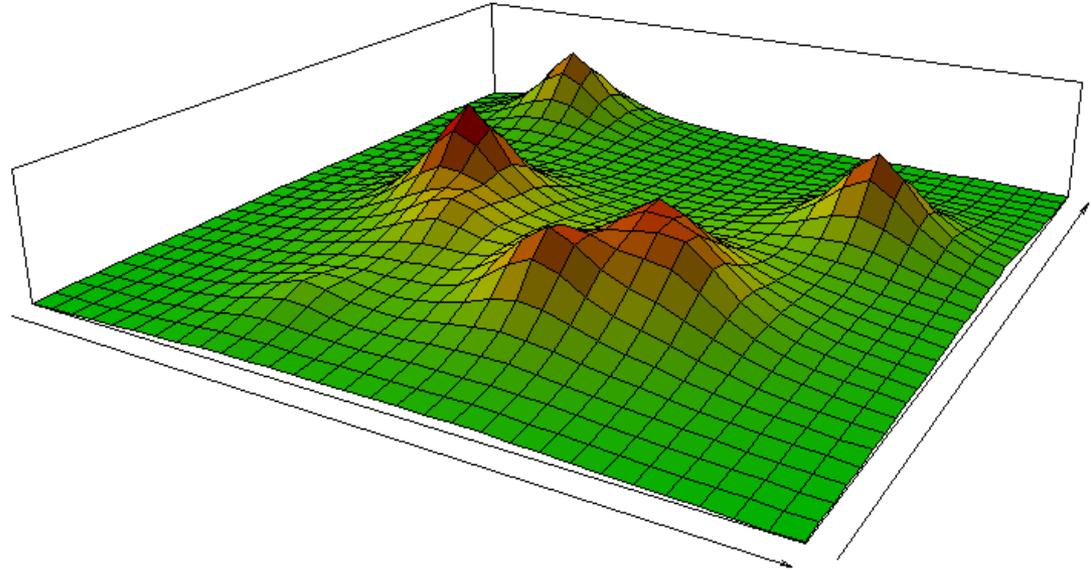
### 3) Relative probability of survival

in a cell is assumed to depend on the presence of the studied crop species in that cell

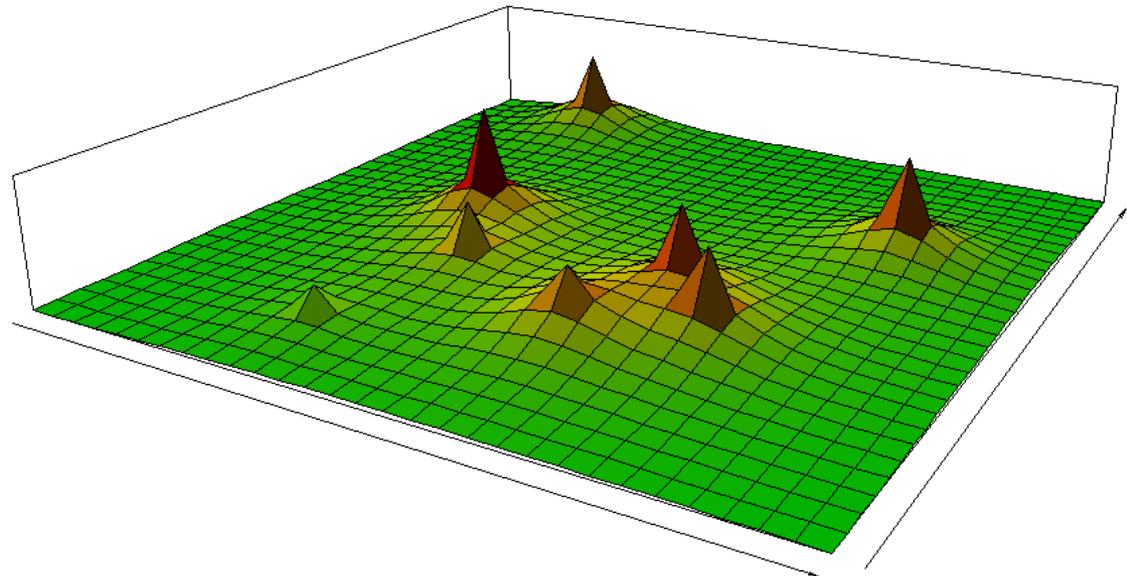
- If host plants are cultivated in the cell, the index remains unchanged
- If host plants are not cultivated in the cell, the index decreases according to a predetermined proportion



## 2. Spread



## 3. Survival



# Relative probability of invasion

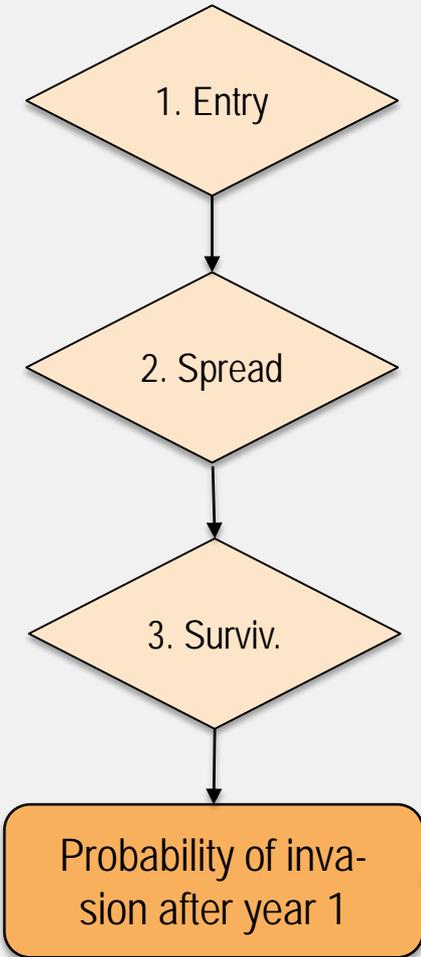
Assessed to each cell followingly

1. Probability of **entry**
2. Probability of **spread**
3. Probability of **survival**

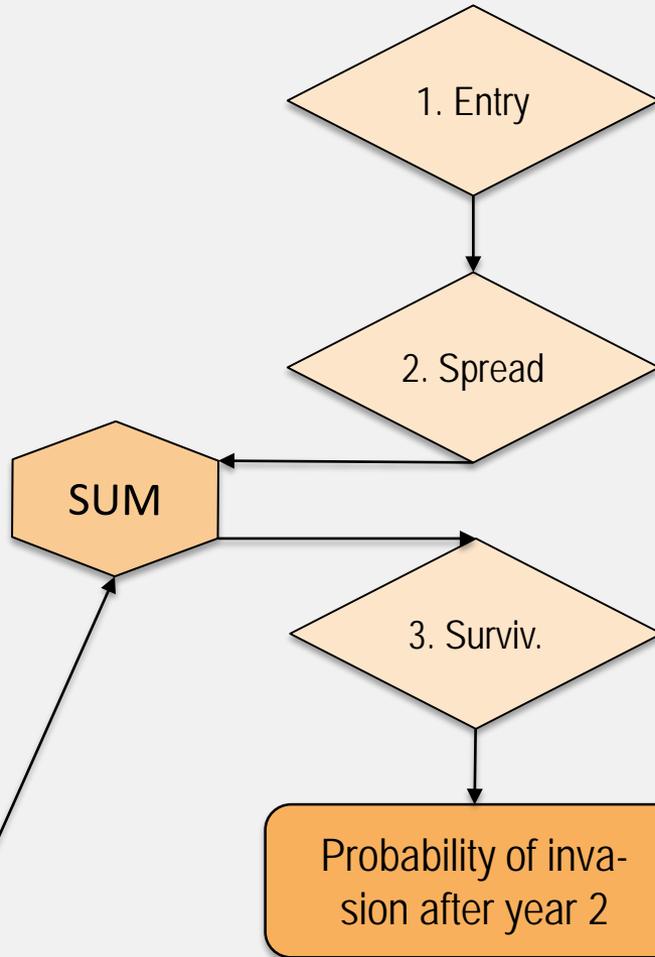
→ Probability of **invasion**

# Accumulation of the probability over the years

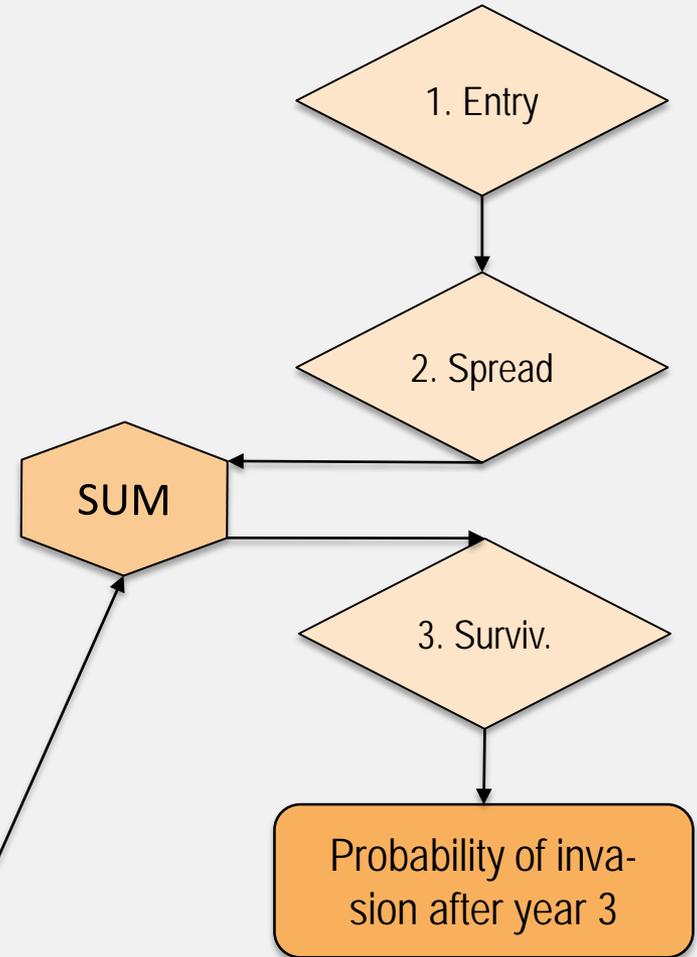
## 1. year



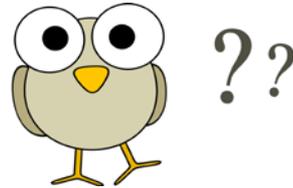
## 2. year



## 3. year



# Uncertainty



## Pest generic approach!

- “fit for all purpose” parameters of **spread** and **survival** cannot be set
- **Simulation of**
- Spread parameter (kernel smoothing) from a uniform distribution (0 – 0.5)
  - Survival parameter from a uniform distribution (0 – 0.5)
- **a distribution of risk index values for each cell**

# Ranking of the cells

- Possible to rank the cells based on the average, or other summary metric
- Yet, if we wish the ranks to represent real differences in the indices, the whole distribution must be used in the ranking by **stochastic ordering techniques**

## Potato as an example (2011-2015)

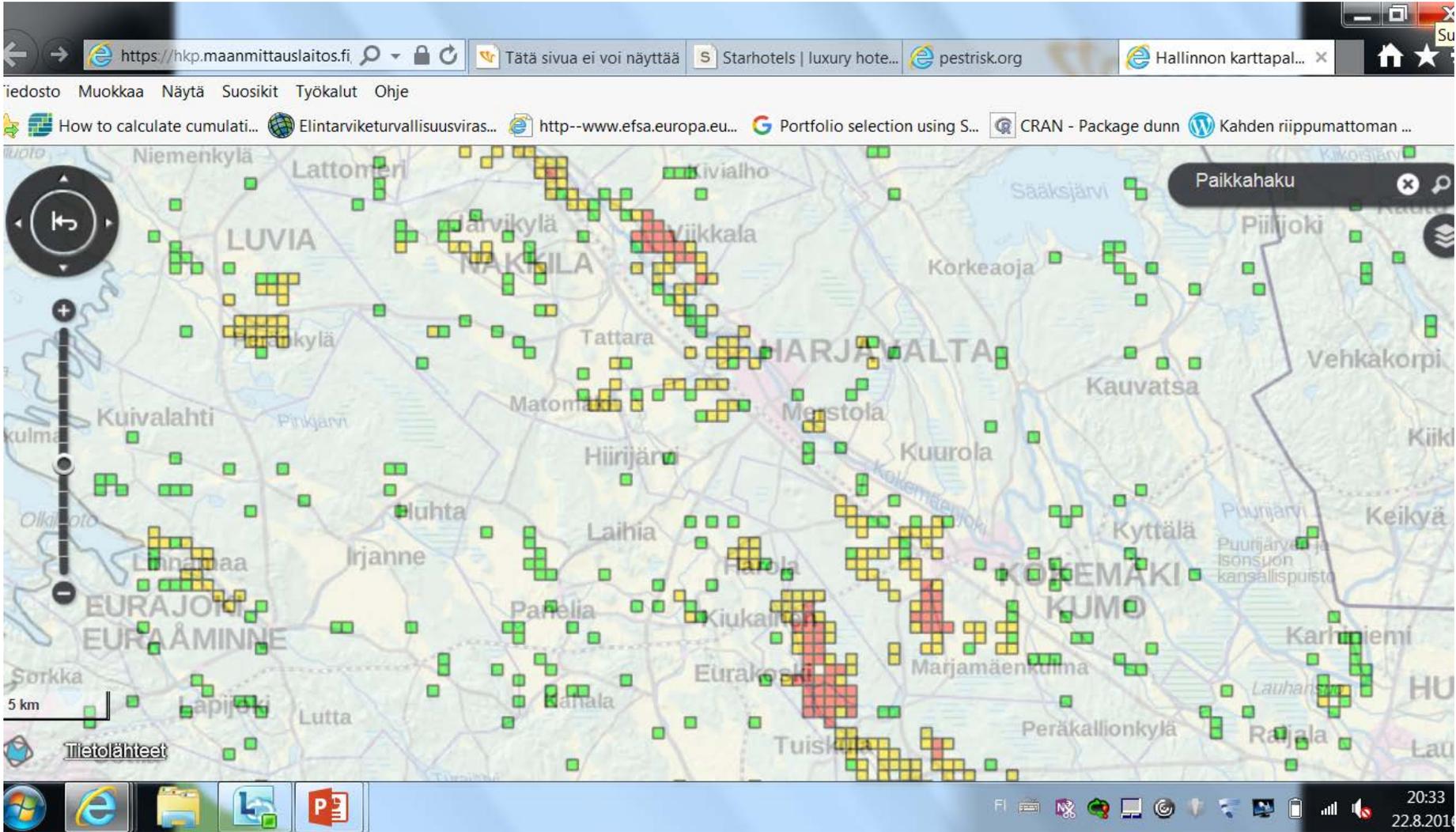


# Summary

- Spatial and temporal distribution of places of production is used to map the invasion probability of pests with risk indices
- Indices do not represent actual probabilities, but they allow comparison of the relative probabilities
- Simple methodology for a practical problem, i.e. targeting phytosanitary surveys

# Kiitos!





The screenshot displays a web browser window with the address bar showing <https://hkp.maanmittauslaitos.fi>. The browser's address bar also contains several tabs, including "Tätä sivua ei voi näyttää", "Starhotels | luxury hote...", "pestrisk.org", and "Hallinnon karttapal...".

The main content area shows a map of Finland, specifically the region around Jyväskylä. The map is overlaid with numerous small, colored squares (green, yellow, and red) representing data points. The map includes labels for various municipalities such as Niemenkylä, Luviala, Harjavalta, and Kouvola. A search bar in the top right corner of the map interface is labeled "Paikkahaku".

The Windows taskbar at the bottom of the screen shows the system tray with the time 20:33 and the date 22.8.2014. The taskbar also displays several application icons, including the Windows Start button, Internet Explorer, File Explorer, and Microsoft PowerPoint.